CONFORMAL BOUNDS FROM ENTANGLEMENT

Pablo Bueno

GRASS-SYMBHOL MEETING 2023 NOVEMBER 16 $^{\rm th}$ 2023



Based on:

[PB, Horacio Casini, Oscar Lasso Andino, Javier Moreno] Phys.Rev.Lett. 131 (2023) 17, 171601

1. INTRODUCTION

Consider a finite quantum system made of two subsystems A, B in some state $|\psi\rangle \in \mathcal{H}_A \otimes \mathcal{H}_B$.

Consider a finite quantum system made of two subsystems A, B in some state $|\psi\rangle \in \mathcal{H}_A \otimes \mathcal{H}_B$.

 $\blacksquare \ \text{If} \ |\psi\rangle \ \text{can be written as} \ |\psi\rangle = |\phi\rangle_{\mathsf{A}} \otimes |\tilde{\phi}\rangle_{\mathsf{B}} \qquad \Longrightarrow \quad |\psi\rangle \ \text{is called separable}.$

Consider a finite quantum system made of two subsystems A, B in some state $|\psi\rangle \in \mathcal{H}_A \otimes \mathcal{H}_B$.

■ If $|\psi\rangle$ can be written as $|\psi\rangle = |\phi\rangle_A \otimes |\tilde{\phi}\rangle_B \implies |\psi\rangle$ is called separable. ■ If $|\psi\rangle$ cannot be written as $|\psi\rangle = |\phi\rangle_A \otimes |\tilde{\phi}\rangle_B \implies |\psi\rangle$ is called entangled.

Consider a finite quantum system made of two subsystems A, B in some state $|\psi\rangle \in \mathcal{H}_A \otimes \mathcal{H}_B$.

- If $|\psi\rangle$ can be written as $|\psi\rangle = |\phi\rangle_A \otimes |\tilde{\phi}\rangle_B \implies |\psi\rangle$ is called separable.
- $\blacksquare \ If |\psi\rangle \ \text{cannot be written as } |\psi\rangle = |\phi\rangle_{\mathsf{A}} \otimes |\tilde{\phi}\rangle_{\mathsf{B}} \quad \Longrightarrow \quad |\psi\rangle \ \text{is called entangled.}$

In the latter case, the state of each subsystem cannot be fully described without the other.

Consider a finite quantum system made of two subsystems A, B in some state $|\psi\rangle \in \mathcal{H}_A \otimes \mathcal{H}_B$.

- If $|\psi\rangle$ can be written as $|\psi\rangle = |\phi\rangle_A \otimes |\tilde{\phi}\rangle_B \implies |\psi\rangle$ is called separable.
- If $|\psi\rangle$ cannot be written as $|\psi\rangle = |\phi\rangle_A \otimes |\tilde{\phi}\rangle_B \implies |\psi\rangle$ is called entangled.

In the latter case, the state of each subsystem cannot be fully described without the other. The two form a single inseparable entity

Consider a finite quantum system made of two subsystems A, B in some state $|\psi\rangle \in \mathcal{H}_A \otimes \mathcal{H}_B$.

- If $|\psi\rangle$ can be written as $|\psi\rangle = |\phi\rangle_A \otimes |\tilde{\phi}\rangle_B \implies |\psi\rangle$ is called separable.
- If $|\psi\rangle$ cannot be written as $|\psi\rangle = |\phi\rangle_A \otimes |\tilde{\phi}\rangle_B \implies |\psi\rangle$ is called entangled.

In the latter case, the state of each subsystem cannot be fully described without the other. The two form a single inseparable entity \Leftrightarrow taking partial traces we loose information.

ENTANGLEMENT IS REAL!



Von Neumann entropy \Leftrightarrow standard notion of entropy associated to any quantum state ρ :

$$S_{
m vN}(
ho)\equiv -\operatorname{Tr}
ho\log
ho$$

Von Neumann entropy \Leftrightarrow standard notion of entropy associated to any quantum state ρ :

$$S_{\rm vN}(
ho) \equiv -\operatorname{Tr}
ho \log
ho$$

• $S_{vN}(\rho) \ge 0$ for any state.

Von Neumann entropy \Leftrightarrow standard notion of entropy associated to any quantum state ρ :

 $S_{\rm vN}(
ho)\equiv -\operatorname{Tr}
ho\log
ho$

S_{vN}(ρ) ≥ 0 for any state.
 S_{vN}(ρ) = 0 if ρ is pure.

Given a system composed of two subsystems A and B in some pure state $\rho_{AB}\text{,}$

$$\mathsf{S}(\mathsf{A})\equiv\mathsf{S}_{\scriptscriptstyle\mathrm{VN}}(
ho_{\mathsf{A}})=-\operatorname{\mathsf{Tr}}_{\mathsf{A}}
ho_{\mathsf{A}}\log
ho_{\mathsf{A}}$$

where $\rho_{\rm A} \equiv {\rm Tr}_{\rm B} \, \rho_{\rm AB}$ is the reduced density matrix.

$$\mathsf{S}(\mathsf{A})\equiv\mathsf{S}_{\scriptscriptstyle\mathrm{VN}}(
ho_{\mathsf{A}})=-\operatorname{\mathsf{Tr}}_{\mathsf{A}}
ho_{\mathsf{A}}\log
ho_{\mathsf{A}}$$

where $\rho_{\rm A} \equiv {\rm Tr}_{\rm B} \, \rho_{\rm AB}$ is the reduced density matrix.

 \blacksquare S(A) quantifies "how entangled" is A with B.

$$\mathsf{S}(\mathsf{A})\equiv\mathsf{S}_{\scriptscriptstyle\mathrm{VN}}(
ho_{\mathsf{A}})=-\operatorname{\mathsf{Tr}}_{\mathsf{A}}
ho_{\mathsf{A}}\log
ho_{\mathsf{A}}$$

where $\rho_{\rm A} \equiv {\rm Tr}_{\rm B} \, \rho_{\rm AB}$ is the reduced density matrix.

- \blacksquare S(A) quantifies "how entangled" is A with B.
- If ρ_{AB} is separable, ρ_A will be pure and then S(A) = 0.

$$\mathsf{S}(\mathsf{A})\equiv\mathsf{S}_{\scriptscriptstyle\mathrm{VN}}(
ho_{\mathsf{A}})=-\operatorname{\mathsf{Tr}}_{\mathsf{A}}
ho_{\mathsf{A}}\log
ho_{\mathsf{A}}$$

where $\rho_{\rm A} \equiv {\rm Tr}_{\rm B} \, \rho_{\rm AB}$ is the reduced density matrix.

- \blacksquare S(A) quantifies "how entangled" is A with B.
- If ρ_{AB} is separable, ρ_A will be pure and then S(A) = 0.
- By definition it satisfies S(A) = S(B).

\star Entanglement in QFT

■ The natural subsystems in QFT are spacetime regions,

The natural subsystems in QFT are spacetime regions, e.g., fix some timeslice Σ, divide it in two regions A and B:



The natural subsystems in QFT are spacetime regions, e.g., fix some timeslice Σ, divide it in two regions A and B:

$$\Sigma$$
 ∂A B ∂A ∂A B

Associated to A there is an algebra of operators $\mathcal{A}(A)$ (associated to B there is another).

The natural subsystems in QFT are spacetime regions, e.g., fix some timeslice Σ, divide it in two regions A and B:

$$\Sigma$$
 ∂A B ∂A ∂A B

Associated to A there is an algebra of operators $\mathcal{A}(A)$ (associated to B there is another).

Given a global state and some region A, one would like to associate a density matrix to $\mathcal{A}(A)$ and compute functionals such as the EE...

■ In QFT the entanglement entropy of subregions is divergent in any state:

 $S(A) = +\infty$.

ENTANGLEMENT IN QFT

■ In QFT the entanglement entropy of subregions is divergent in any state:

 $S(A) = +\infty$.

• Any state is intrinsically and infinitely entangled across $\mathcal{A}(A)$ and $\mathcal{A}(B)$.

ENTANGLEMENT IN QFT

■ In QFT the entanglement entropy of subregions is divergent in any state:

 $S(A) = +\infty$.

- Any state is intrinsically and infinitely entangled across $\mathcal{A}(A)$ and $\mathcal{A}(B)$.
- We can either regulate the theory (e.g., in the lattice) or consider alternative well-defined measures.

ENTANGLEMENT IN QFT

■ In QFT the entanglement entropy of subregions is divergent in any state:

 $S(A) = +\infty$.

- Any state is intrinsically and infinitely entangled across $\mathcal{A}(A)$ and $\mathcal{A}(B)$.
- We can either regulate the theory (e.g., in the lattice) or consider alternative well-defined measures.
- In a general QFT in *d* dimensions, in any state, the EE of any spacetime region *A* has the structure:

$$S^{(d)}(A) = b_{d-2} \frac{L^{d-2}}{\delta^{d-2}} + b_{d-4} \frac{L^{d-4}}{\delta^{d-4}} + \dots + \begin{cases} b_1 \frac{L}{\delta} + (-1)^{\frac{d-1}{2}} \mathbf{S}^{\text{univ}}, & \text{(odd } d), \\ b_2 \frac{L^2}{\delta^2} + (-1)^{\frac{d-2}{2}} \mathbf{S}^{\text{univ}} \log\left(\frac{L}{\delta}\right) + b_0, & \text{(even } d). \end{cases}$$

where L is some characteristic length of A and δ is a UV regulator.

ENTANGLEMENT IN THREE-DIMENSIONAL CFTS

Let us focus on d = 3 conformal field theories (CFTs).

ENTANGLEMENT IN THREE-DIMENSIONAL CFTS

Let us focus on *d* = 3 conformal field theories (CFTs). ■ The vacuum EE of some region A is given by:

$$S^{(d=3)}(A) = b_1 \cdot \frac{\operatorname{perimeter}(\partial A)}{\delta} - F(A) + O(\delta)$$

$$S^{(d=3)}(A) = b_1 \cdot \frac{\operatorname{perimeter}(\partial A)}{\delta} - F(A) + O(\delta)$$

• We will be interested in the universal term, F(A).

8

$$S^{(d=3)}(A) = b_1 \cdot \frac{\operatorname{perimeter}(\partial A)}{\delta} - F(A) + O(\delta)$$

- We will be interested in the universal term, F(A).
- It is not possible to resolve A with more precision than the one determined by δ :

$$S^{(d=3)}(A) = b_1 \cdot \frac{\operatorname{perimeter}(\partial A)}{\delta} - F(A) + O(\delta)$$

- We will be interested in the universal term, F(A).
- It is not possible to resolve A with more precision than the one determined by δ : perimeter and perimeter $(1 + a\delta)$ with $a \sim O(1)$ cannot be distinguished.

$$S^{(d=3)}(A) = b_1 \cdot \frac{\operatorname{perimeter}(\partial A)}{\delta} - F(A) + O(\delta)$$

• We will be interested in the universal term, F(A).

8

■ It is not possible to resolve A with more precision than the one determined by δ : perimeter and perimeter $(1 + a\delta)$ with $a \sim O(1)$ cannot be distinguished. This uncertainty pollutes F(A) via the area-law term:

$$F(A) \rightarrow F(A) - a \cdot b_1 \cdot \operatorname{perimeter}(\partial A)$$
ENTANGLEMENT IN THREE-DIMENSIONAL CFTS

In order to define F(A) rigorously, we can use mutual information,

$$I(A,B) \equiv S(A) + S(B) - S(A \cup B)$$

which is well-defined in the continuum.

ENTANGLEMENT IN THREE-DIMENSIONAL CFTS

In order to define F(A) rigorously, we can use mutual information,

$$I(A,B) \equiv S(A) + S(B) - S(A \cup B)$$

which is well-defined in the continuum.



In order to define F(A) rigorously, we can use mutual information,

$$I(A,B) \equiv S(A) + S(B) - S(A \cup B)$$

which is well-defined in the continuum.



Robust definition of **F**(**A**):

$$I(A^+, A^-) = \kappa \int_{\partial A} \frac{\mathrm{d}s}{\varepsilon(s)} - 2F(A) + \mathcal{O}(\varepsilon) \,.$$

[Casini, Huerta, Myers, Yale]

2. ENTANGLEMENT ENTROPY SHAPE DEPENDENCE

Which shape minimizes F(A)?





• Let $F_o \equiv F(\text{round disk})$.

- Let $F_o \equiv F(\text{round disk})$.
- This coincides with the Euclidean free energy on the round sphere for general theories: [Casini, Huerta, Myers]

$$F_{o} = -\log Z_{S^{3}} \quad \forall \operatorname{CFT}_{3}$$

- Let $F_o \equiv F(\text{round disk})$.
- This coincides with the Euclidean free energy on the round sphere for general theories: [Casini, Huerta, Myers]

$$\mathsf{F}_{\mathsf{o}} = -\log Z_{\mathbb{S}^3} \quad \forall \ \mathrm{CFT}_3$$

• "Natural" to expect that $F(A) \ge F_o \forall$ region A.

- Let $F_o \equiv F(\text{round disk})$.
- This coincides with the Euclidean free energy on the round sphere for general theories: [Casini, Huerta, Myers]

$$\mathsf{F}_{\mathsf{o}} = -\log Z_{\mathbb{S}^3} \quad \forall \operatorname{CFT}_3$$

• "Natural" to expect that $F(A) \ge F_o \forall$ region A. Previous evidence from holographic theories [Alexakis, Mazzeo; Astaneh, Gibbons, Solodukhin],

- Let $F_o \equiv F(\text{round disk})$.
- This coincides with the Euclidean free energy on the round sphere for general theories: [Casini, Huerta, Myers]

$$\mathsf{F}_{\mathsf{o}} = -\log Z_{\mathbb{S}^3} \quad \forall \operatorname{CFT}_3$$

• "Natural" to expect that $F(A) \ge F_o \forall$ region A. Previous evidence from holographic theories [Alexakis, Mazzeo; Astaneh, Gibbons, Solodukhin], small deformations of disk regions [Mezei],

- Let $F_o \equiv F(\text{round disk})$.
- This coincides with the Euclidean free energy on the round sphere for general theories: [Casini, Huerta, Myers]

$$F_{o} = -\log Z_{S^{3}} \quad \forall \operatorname{CFT}_{3}$$

• "Natural" to expect that $F(A) \ge F_o \forall$ region A. Previous evidence from holographic theories [Alexakis, Mazzeo; Astaneh, Gibbons, Solodukhin], small deformations of disk regions [Mezei], regions with sharp features,

Which shape minimizes F(A)?

the EMI model...



$$\forall \operatorname{CFT}_3, \quad \forall \operatorname{region} A : \quad \frac{F(A)}{F_0} \ge 1,$$

[PB, Casini, Moreno, Lasso Andino]

 $\forall \text{ CFT}_3, \quad \forall \text{ region } A: \quad \frac{F(A)}{F_o} \ge 1, \quad \text{with } \quad \frac{F(A)}{F_o} = 1 \Leftrightarrow A = \text{round disk}$

[PB, Casini, Moreno, Lasso Andino]

$$\forall \ \mathrm{CFT}_3, \quad \forall \ \mathrm{region} \ A: \quad \frac{F(A)}{F_o} \geq 1 \,, \quad \text{with} \quad \frac{F(A)}{F_o} = 1 \Leftrightarrow A = \mathrm{round} \ \mathrm{disk}$$

For regions with $n_{\partial A}$ connected boundaries, the bound can be improved:

[PB, Casini, Moreno, Lasso Andino]

$$\forall \text{ CFT}_3, \quad \forall \text{ region } A: \quad \frac{F(A)}{F_o} \geq 1 \,, \quad \text{with } \quad \frac{F(A)}{F_o} = 1 \Leftrightarrow A = \text{round disk}$$

For regions with $n_{\partial A}$ connected boundaries, the bound can be improved:

 $\forall \text{ CFT}_3, \forall \text{ region } A : F(A) \ge n_{\partial A}F_0$

3. CONFORMAL BOUNDS FROM ENTANGLEMENT

\star Conformal bounds

 Originally obtained from positivity of energy flux escaping at infinity for states resulting from local insertions of the stress tensor on the vacuum

■ Originally obtained from positivity of energy flux escaping at infinity for states resulting from local insertions of the stress tensor on the vacuum ⇒ constraints on **local** correlators' (*TT*) and (*TTT*) coefficients.

[Hofman, Maldacena]

■ Originally obtained from positivity of energy flux escaping at infinity for states resulting from local insertions of the stress tensor on the vacuum ⇒ constraints on **local** correlators' (*TT*) and (*TTT*) coefficients.

[Hofman, Maldacena]

■ Rigorous proof using bootstrap methods [Hofman, Li, Meltzer, Poland, Rejon-Barrera]

■ Originally obtained from positivity of energy flux escaping at infinity for states resulting from local insertions of the stress tensor on the vacuum ⇒ constraints on **local** correlators' (*TT*) and (*TTT*) coefficients.

[Hofman, Maldacena]

Rigorous proof using bootstrap methods [Hofman, Li, Meltzer, Poland, Rejon-Barrera] Prototypical example in d = 4 for trace-anomaly coefficients

$$\langle T^{\mu}_{\mu}
angle = -rac{\mathbf{a}}{\mathbf{16}\pi^2} \mathcal{X}_4 + rac{\mathbf{c}}{\mathbf{16}\pi^2} \mathbf{C}_{\mu
u
ho\sigma} \mathbf{C}^{\mu
u
ho\sigma}$$

■ Originally obtained from positivity of energy flux escaping at infinity for states resulting from local insertions of the stress tensor on the vacuum ⇒ constraints on **local** correlators' (*TT*) and (*TTT*) coefficients.

[Hofman, Maldacena]

Rigorous proof using bootstrap methods [Hofman, Li, Meltzer, Poland, Rejon-Barrera] Prototypical example in d = 4 for trace-anomaly coefficients

$$\langle T^{\mu}_{\mu}
angle = -rac{a}{16\pi^2} \mathcal{X}_4 + rac{c}{16\pi^2} C_{\mu
u
ho\sigma} C^{\mu
u
ho\sigma}$$

Universal bound:

$$\left| \frac{c}{a} \right|_{Maxwell} \le \frac{c}{a} \le \frac{c}{a} \Big|_{free \, scalar} \quad \forall \, \mathrm{CFT}_4$$

3.1 A NEW CONJECTURE

A NEW CONJECTURE

♦ Conjecture:

$$\left. \frac{F(A)}{F_{o}} \right|_{Maxwell} \leq \frac{F(A)}{F_{o}} \leq \left. \frac{F(A)}{F_{o}} \right|_{free \, scalar} \quad \forall \, \mathrm{CFT}_{3} \quad \forall \, \mathrm{region} \; A$$

3.2 HINTS FROM FOUR DIMENSIONS

$$rac{\mathsf{S}^{\mathcal{4d}}_{\mathrm{univ}}(\mathsf{A})}{oldsymbol{a}} = rac{\mathsf{1}}{\pi} \left[\mathcal{W}_{\partial \mathsf{A}} + \left(rac{\mathsf{C}}{oldsymbol{a}} - \mathsf{1}
ight) rac{\mathcal{K}_{\partial \mathsf{A}}}{\mathsf{2}}
ight] \,,$$

$$rac{\mathsf{S}^{4d}_{ ext{univ}}(\mathsf{A})}{oldsymbol{a}} = rac{\mathsf{1}}{\pi} \left[\mathcal{W}_{\partial \mathsf{A}} + \left(rac{\mathsf{c}}{oldsymbol{a}} - \mathsf{1}
ight) rac{\mathcal{K}_{\partial \mathsf{A}}}{\mathsf{2}}
ight] \,,$$

 $\mathcal{W}_{\partial A}$ and $\mathcal{K}_{\partial A}$ are fixed positive definite and positive semidefinite respectively,

$$rac{\mathsf{S}^{4d}_{ ext{univ}}(\mathsf{A})}{oldsymbol{a}} = rac{\mathsf{1}}{\pi} \left[\mathcal{W}_{\partial \mathsf{A}} + \left(rac{\mathsf{c}}{oldsymbol{a}} - \mathsf{1}
ight) rac{\mathcal{K}_{\partial \mathsf{A}}}{\mathsf{2}}
ight] \,,$$

 $W_{\partial A}$ and $\mathcal{K}_{\partial A}$ are fixed positive definite and positive semidefinite respectively, so an analogous conjecture to ours:

$$\frac{S_{\mathrm{univ}}^{4d}(A)}{a}\bigg|_{Maxwell} \leq \frac{S_{\mathrm{univ}}^{4d}(A)}{a} \leq \frac{S_{\mathrm{univ}}^{4d}(A)}{a}\bigg|_{free \, scalar} \quad \forall \, \mathrm{CFT}_4 \quad \forall \, \mathrm{region} \; A$$

$$rac{\mathsf{S}^{4d}_{ ext{univ}}(\mathsf{A})}{oldsymbol{a}} = rac{\mathsf{1}}{\pi} \left[\mathcal{W}_{\partial \mathsf{A}} + \left(rac{\mathsf{c}}{oldsymbol{a}} - \mathsf{1}
ight) rac{\mathcal{K}_{\partial \mathsf{A}}}{\mathsf{2}}
ight] \,,$$

 $W_{\partial A}$ and $\mathcal{K}_{\partial A}$ are fixed positive definite and positive semidefinite respectively, so an analogous conjecture to ours:

$$\frac{S_{\mathrm{univ}}^{4d}(A)}{a}\bigg|_{Maxwell} \leq \frac{S_{\mathrm{univ}}^{4d}(A)}{a} \leq \frac{S_{\mathrm{univ}}^{4d}(A)}{a}\bigg|_{\text{free scalar}} \quad \forall \text{ CFT}_4 \quad \forall \text{ region } A$$

is trivially equivalent to the HM bounds!

3.3 Orbifold theories and multicomponent REGIONS

Consider a theory $\rm O$ obtained from quotienting some complete theory $\rm C$ by some finite symmetry group G.

Consider a theory $\rm O$ obtained from quotienting some complete theory $\rm C$ by some finite symmetry group G.

■ The mutual information is given by [Casini, Huerta, Magan, Pontello]

$$I^{\mathrm{O}}(\mathsf{A}^+,\mathsf{A}^-) = I^{\mathrm{C}}(\mathsf{A}^+,\mathsf{A}^-) - n_{\partial \mathsf{A}} \log |\mathsf{G}| + \Delta\,, \quad \Delta \geq \mathsf{O}$$

Consider a theory ${\rm O}$ obtained from quotienting some complete theory ${\rm C}$ by some finite symmetry group G.

■ The mutual information is given by [Casini, Huerta, Magan, Pontello]

$$I^{\mathrm{O}}(\mathsf{A}^+,\mathsf{A}^-) = I^{\mathrm{C}}(\mathsf{A}^+,\mathsf{A}^-) - n_{\partial\mathsf{A}}\log|\mathsf{G}| + \Delta\,,\quad\Delta\geq\mathsf{O}$$

• Using the definition of F(A) from the MI, one finds

$$\left. n_{\partial \mathsf{A}} \leq \left. \frac{\mathsf{F}(\mathsf{A})}{\mathsf{F}_{\mathsf{o}}} \right|_{\mathrm{O}} \leq \left. \frac{\mathsf{F}(\mathsf{A})|_{\mathrm{C}} + \frac{n_{\partial \mathsf{A}}}{2} \log |\mathsf{G}|}{\mathsf{F}_{\mathsf{o}}|_{\mathrm{C}} + \frac{1}{2} \log |\mathsf{G}|} \leq \left. \frac{\mathsf{F}(\mathsf{A})}{\mathsf{F}_{\mathsf{o}}} \right|_{\mathrm{C}} \right.$$
Consider a theory ${\rm O}$ obtained from quotienting some complete theory ${\rm C}$ by some finite symmetry group G.

■ The mutual information is given by [Casini, Huerta, Magan, Pontello]

$$I^{\mathrm{O}}(\mathsf{A}^+,\mathsf{A}^-) = I^{\mathrm{C}}(\mathsf{A}^+,\mathsf{A}^-) - n_{\partial\mathsf{A}}\log|\mathsf{G}| + \Delta\,,\quad\Delta\geq\mathsf{O}$$

• Using the definition of F(A) from the MI, one finds

$$n_{\partial \mathsf{A}} \leq \left. \frac{\mathsf{F}(\mathsf{A})}{\mathsf{F}_{\mathsf{o}}} \right|_{\mathrm{O}} \leq \frac{\mathsf{F}(\mathsf{A})|_{\mathrm{C}} + \frac{n_{\partial \mathsf{A}}}{2} \log |\mathsf{G}|}{\mathsf{F}_{\mathsf{o}}|_{\mathrm{C}} + \frac{1}{2} \log |\mathsf{G}|} \leq \left. \frac{\mathsf{F}(\mathsf{A})}{\mathsf{F}_{\mathsf{o}}} \right|_{\mathrm{C}}$$

Hence, the ratio F(A)/F_o for the parent theory is always greater than the one for the orbifold theory.

■ The same happens for infinite symmetry groups.

The same happens for infinite symmetry groups.
 The Maxwell theory is an orbifold of the free scalar under ℝ implementing φ → φ + δ.

- The same happens for infinite symmetry groups.
- The Maxwell theory is an orbifold of the free scalar under \mathbb{R} implementing $\phi \rightarrow \phi + \delta$.
- One has: $F(A)|_{Maxwell} = F(A)|_{free \, scalar} + n_{\partial A}/4 \log(-\log(\delta))$,

- The same happens for infinite symmetry groups.
- The Maxwell theory is an orbifold of the free scalar under \mathbb{R} implementing $\phi \rightarrow \phi + \delta$.
- One has: $F(A)|_{Maxwell} = F(A)|_{free scalar} + n_{\partial A}/4 \log(-\log(\delta))$, and from this:

$$\frac{F(A)}{F_{o}}\Big|_{Maxwell} = n_{\partial A}$$

- The same happens for infinite symmetry groups.
- The Maxwell theory is an orbifold of the free scalar under \mathbb{R} implementing $\phi \rightarrow \phi + \delta$.
- One has: $F(A)|_{Maxwell} = F(A)|_{free \, scalar} + n_{\partial A}/4 \log(-\log(\delta))$, and from this: $\frac{F(A)}{F_o}\Big|_{Maxwell} = n_{\partial A}$
- Hence, the lower bound is equivalent to the improved general bound for topologically non-trivial regions.



$$\left| n_{\partial \mathsf{A}} \leq \frac{F(\mathsf{A})}{F_{\mathsf{o}}} \leq \frac{F(\mathsf{A})}{F_{\mathsf{o}}} \right|_{\mathsf{free \, scalar}} \quad \forall \ \mathrm{CFT}_{\mathsf{3}} \quad \forall \ \mathrm{region} \ \mathsf{A}$$

$$\left| n_{\partial \mathsf{A}} \leq \frac{F(\mathsf{A})}{F_{\mathsf{O}}} \leq \frac{F(\mathsf{A})}{F_{\mathsf{O}}} \right|_{\mathsf{free \, scalar}} \quad \forall \ \mathrm{CFT}_{\mathsf{3}} \quad \forall \ \mathrm{region} \ \mathsf{A}$$

Lower bound not conjectural

$$\left| n_{\partial \mathsf{A}} \leq \frac{F(\mathsf{A})}{F_{\mathsf{o}}} \leq \frac{F(\mathsf{A})}{F_{\mathsf{o}}} \right|_{\mathsf{free \, scalar}} \quad \forall \ \mathrm{CFT}_{\mathsf{3}} \quad \forall \ \mathrm{region} \ \mathsf{A}$$

Lower bound not conjectural (follows from the general shape-dependence results).

3.4 DISCONNECTED REGIONS

• Consider region with two disconnected components: $A = A_1 \cup A_2$.

■ Consider region with two disconnected components: $A = A_1 \cup A_2$. ■ Then, $S(A_1 \cup A_2) = S(A_1) + S(A_2) - I(A_1, A_2)$.

Consider region with two disconnected components: $A = A_1 \cup A_2$. Then, $S(A_1 \cup A_2) = S(A_1) + S(A_2) - I(A_1, A_2)$. If A_1 and A_2 are disks:

$$\frac{F(A_1 \cup A_2)}{F_0} = 2 + \frac{I(A_1, A_2)}{F_0}$$

Consider region with two disconnected components: $A = A_1 \cup A_2$. Then, $S(A_1 \cup A_2) = S(A_1) + S(A_2) - I(A_1, A_2)$. If A_1 and A_2 are disks:

$$\frac{F(A_1\cup A_2)}{F_0}=2+\frac{I(A_1,A_2)}{F_0}$$

• For long separations, free scalar provides greatest value of $I(A_1, A_2)$.

Consider region with two disconnected components: $A = A_1 \cup A_2$. Then, $S(A_1 \cup A_2) = S(A_1) + S(A_2) - I(A_1, A_2)$. If A_1 and A_2 are disks:

$$\frac{F(A_1\cup A_2)}{F_0}=2+\frac{I(A_1,A_2)}{F_0}$$

For long separations, free scalar provides greatest value of $I(A_1, A_2)$. In general: [Cardy; Agon, Faulkner]

 $I(A_1,A_2) \sim |r_{A_1} - r_{A_2}|^{-4\Delta_{
m CFT_3}}$ where $\Delta_{
m CFT_3} \equiv$ smallest scaling dimension

Consider region with two disconnected components: $A = A_1 \cup A_2$. Then, $S(A_1 \cup A_2) = S(A_1) + S(A_2) - I(A_1, A_2)$. If A_1 and A_2 are disks:

$$\frac{F(A_1 \cup A_2)}{F_0} = 2 + \frac{I(A_1, A_2)}{F_0}$$

■ For long separations, free scalar provides greatest value of *I*(*A*₁, *A*₂). In general: [Cardy; Agon, Faulkner]

 $I(A_1, A_2) \sim |r_{A_1} - r_{A_2}|^{-4\Delta_{CFT_3}}$ where $\Delta_{CFT_3} \equiv$ smallest scaling dimension Now, \forall CFT₃ one has

Consider region with two disconnected components: $A = A_1 \cup A_2$. Then, $S(A_1 \cup A_2) = S(A_1) + S(A_2) - I(A_1, A_2)$. If A_1 and A_2 are disks:

$$\frac{F(A_1\cup A_2)}{F_0}=2+\frac{I(A_1,A_2)}{F_0}$$

■ For long separations, free scalar provides greatest value of *I*(*A*₁, *A*₂). In general: [Cardy; Agon, Faulkner]

 $I(A_1, A_2) \sim |r_{A_1} - r_{A_2}|^{-4\Delta_{CFT_3}}$ where $\Delta_{CFT_3} \equiv$ smallest scaling dimension Now, \forall CFT₃ one has

$$\Delta_{\mathrm{CFT}_3} \geq \Delta_{\mathrm{free\,scalar}} = rac{(d-2)}{2}$$
 (unitarity bound)

Consider region with two disconnected components: $A = A_1 \cup A_2$. Then, $S(A_1 \cup A_2) = S(A_1) + S(A_2) - I(A_1, A_2)$. If A_1 and A_2 are disks:

$$\frac{F(A_1 \cup A_2)}{F_0} = 2 + \frac{I(A_1, A_2)}{F_0}$$

■ For long separations, free scalar provides greatest value of *I*(*A*₁, *A*₂). In general: [Cardy; Agon, Faulkner]

 $I(A_1, A_2) \sim |r_{A_1} - r_{A_2}|^{-4\Delta_{CFT_3}}$ where $\Delta_{CFT_3} \equiv$ smallest scaling dimension Now, \forall CFT₃ one has

$$\Delta_{\mathrm{CFT}_3} \geq \Delta_{\mathrm{free \, scalar}} = rac{(d-2)}{2}$$
 (unitarity bound)

Then, $F(A_1 \cup A_2)/F_0$ is absolutely maximized by the free scalar.

Consider region with two disconnected components: $A = A_1 \cup A_2$. Then, $S(A_1 \cup A_2) = S(A_1) + S(A_2) - I(A_1, A_2)$. If A_1 and A_2 are disks:

$$\frac{F(A_1 \cup A_2)}{F_0} = 2 + \frac{I(A_1, A_2)}{F_0}$$

■ For long separations, free scalar provides greatest value of *I*(*A*₁, *A*₂). In general: [Cardy; Agon, Faulkner]

 $I(A_1, A_2) \sim |r_{A_1} - r_{A_2}|^{-4\Delta_{CFT_3}}$ where $\Delta_{CFT_3} \equiv$ smallest scaling dimension Now, \forall CFT₃ one has

$$\Delta_{
m CFT_3} \geq \Delta_{
m free\,scalar} = rac{(d-2)}{2}$$
 (unitarity bound)

Then, F(A₁ ∪ A₂)/F₀ is absolutely maximized by the free scalar.
 Also holds for general shapes if it holds for A₁ and A₂ individually.

■ Let $A_1(\delta, \epsilon)$ be the causal cone of some disk region A to which one has removed a conical frustrum of angle ϵ and radial height δ .

■ Let $A_1(\delta, \epsilon)$ be the causal cone of some disk region A to which one has removed a conical frustrum of angle ϵ and radial height δ . Let A_2 be some other disk region and $A = A_1(\delta, \epsilon) \cup A_2$.

■ Let $A_1(\delta, \epsilon)$ be the causal cone of some disk region A to which one has removed a conical frustrum of angle ϵ and radial height δ . Let A_2 be some other disk region and $A = A_1(\delta, \epsilon) \cup A_2$. Then, the so-called "pinching property" implies that: [Casini, Teste, Torroba]

$$\frac{F(\lim_{\epsilon \to 0} \lim_{\delta \to 0} A)}{F_0} = 2, \qquad \text{(interacting CFTs)}$$
$$\frac{F(\lim_{\epsilon \to 0} \lim_{\delta \to 0} A)}{F_0} = 2 + \frac{I(A_1, A_2)}{F_0}, \quad \text{(free CFTs)}$$

■ Let $A_1(\delta, \epsilon)$ be the causal cone of some disk region A to which one has removed a conical frustrum of angle ϵ and radial height δ . Let A_2 be some other disk region and $A = A_1(\delta, \epsilon) \cup A_2$. Then, the so-called "pinching property" implies that: [Casini, Teste, Torroba]

$$\begin{split} \frac{F(\lim_{\epsilon \to 0} \lim_{\delta \to 0} A)}{F_0} &= 2, \\ \frac{F(\lim_{\epsilon \to 0} \lim_{\delta \to 0} A)}{F_0} &= 2 + \frac{I(A_1, A_2)}{F_0}, \end{split} \text{ (interacting CFTs)} \end{split}$$

regardless of the separation between A_1 and A_2 .

■ Let $A_1(\delta, \epsilon)$ be the causal cone of some disk region A to which one has removed a conical frustrum of angle ϵ and radial height δ . Let A_2 be some other disk region and $A = A_1(\delta, \epsilon) \cup A_2$. Then, the so-called "pinching property" implies that: [Casini, Teste, Torroba]

$$\begin{split} \frac{F(\lim_{\epsilon \to 0} \lim_{\delta \to 0} A)}{F_0} &= 2, \\ \frac{F(\lim_{\epsilon \to 0} \lim_{\delta \to 0} A)}{F_0} &= 2 + \frac{I(A_1, A_2)}{F_0}, \quad \text{(free CFTs)} \end{split}$$

regardless of the separation between A_1 and A_2 .

■ In this case, *F*(*A*)/*F*_o is smaller for any interacting CFT than for any free one.

■ Now, strong numerical evidence suggests that:

[Agon, PB, Lasso Andino, Vilar Lopez]



for arbitrary spatial regions A_1, A_2 .

■ Now, strong numerical evidence suggests that:

[Agon, PB, Lasso Andino, Vilar Lopez]

$$\left. \frac{I(A_1, A_2)}{F_0} \right|_{
m free \, fermion} < \left. \frac{I(A_1, A_2)}{F_0} \right|_{
m free \, scala}$$

for arbitrary spatial regions A_1, A_2 .

• Once again the free scalar provides an absolute maximum for $F(A)/F_0$.

3.5 CONNECTED REGIONS

\star Small deformations of a disk region

SMALL DEFORMATIONS OF A DISK REGION

Consider general slightly deformed disks

$$\frac{r(\theta)}{R} = 1 + \frac{\epsilon}{\sqrt{\pi}} \sum_{\ell} [a_{\ell,(c)} \cos(\ell\theta) + a_{\ell,(s)} \sin(\ell\theta)], \quad (\epsilon \ll 1)$$

SMALL DEFORMATIONS OF A DISK REGION

Consider general slightly deformed disks

$$\frac{r(\theta)}{R} = 1 + \frac{\epsilon}{\sqrt{\pi}} \sum_{\ell} [a_{\ell,(c)} \cos(\ell\theta) + a_{\ell,(s)} \sin(\ell\theta)], \quad (\epsilon \ll 1)$$

 \blacksquare Then, at leading order in ϵ , we have [Mezei; Faulkner, Leigh, Parrikar]

$$\frac{F(\mathsf{A})}{F_{\mathsf{o}}} = 1 + \frac{\pi^3}{24} \frac{\mathsf{C}_{\mathsf{r}}}{\mathsf{F}_{\mathsf{o}}} \sum_{\ell} \ell(\ell^2 - 1) \left[a_{\ell,(\mathsf{c})}^2 + a_{\ell,(\mathsf{s})}^2 \right] \epsilon^2 \,,$$

SMALL DEFORMATIONS OF A DISK REGION

Consider general slightly deformed disks

$$\frac{r(\theta)}{R} = 1 + \frac{\epsilon}{\sqrt{\pi}} \sum_{\ell} [a_{\ell,(c)} \cos(\ell\theta) + a_{\ell,(s)} \sin(\ell\theta)], \quad (\epsilon \ll 1)$$

Then, at leading order in ϵ , we have [Mezei; Faulkner, Leigh, Parrikar]

$$\frac{F(A)}{F_{o}} = 1 + \frac{\pi^{3}}{24} \frac{C_{\tau}}{F_{o}} \sum_{\ell} \ell(\ell^{2} - 1) \left[a_{\ell,(c)}^{2} + a_{\ell,(s)}^{2}\right] \epsilon^{2},$$

where C_{τ} controls, for a general CFT, the stress-tensor two-point function,

$$\left\langle \mathsf{T}_{\mu
u}(\mathsf{x})\mathsf{T}_{
ho\sigma}(\mathsf{O})
ight
angle_{\mathbb{R}^3} = rac{\mathsf{C}_{\mathsf{T}}}{\mathsf{x}^6} \left[I_{\mu(
ho}I_{\sigma)
u} - rac{\delta_{\mu
u}\delta_{
ho\sigma}}{3}
ight] \,,$$

From our general conjecture it follows that:

$$0 \leq \frac{C_{T}}{F_{0}} \leq \frac{C_{T}}{F_{0}} \bigg|_{\text{free scalar}} = \frac{3}{4\pi^{2} \log 2 - 6\zeta[3]} \simeq 0.14887 \dots$$

From our general conjecture it follows that:

$$0 \leq \frac{C_{T}}{F_{0}} \leq \frac{C_{T}}{F_{0}} \bigg|_{\text{free scalar}} = \frac{3}{4\pi^{2} \log 2 - 6\zeta[3]} \simeq 0.14887 \dots$$

New three-dimensional version of HM bounds!

CONFORMAL BOUNDS IN THREE DIMENSIONS



CONFORMAL BOUNDS IN THREE DIMENSIONS



*** ELLIPSES AND CORNERS**

Moving from the perturbeddisks regime, values of F(A)/F_o for more complicated regions exist in some cases, at least for a few theories.

24

23

- Moving from the perturbeddisks regime, values of F(A)/F_o for more complicated regions exist in some cases, at least for a few theories.
- The conjectural bounds are always satisfied.

24

23

ELLIPSES AND CORNERS

- Moving from the perturbeddisks regime, values of F(A)/F_o for more complicated regions exist in some cases, at least for a few theories.
- The conjectural bounds are always satisfied.



23

4. FUTURE

Find additional evidence/general proof/counterexample

Find additional evidence/general proof/counterexample
 More restrictive upper bound for SUSY theories?

Find additional evidence/general proof/counterexample
 More restrictive upper bound for SUSY theories?
 Analogous conjecture in d = 5 CFTs?

- Find additional evidence/general proof/counterexample
- More restrictive upper bound for SUSY theories?
- Analogous conjecture in d = 5 CFTs?
- Bounds on other ratios of seemingly unrelated universal quantities?

THE END